# Errata for AutoML Pipeline Selection: Efficiently Navigating the Combinatorial Space 

This is the errata for AutoML Pipeline Selection: Efficiently Navigating the Combinatorial Space in the ACM digital library, at https://dl.acm.org/doi/abs/10.1145/3394486.3403197. We apologize for the inconvenience this may have caused. If you have further doubts, please do not hesitate to email the author Chengrun Yang at [cy438 at cornell dot edu].

1. In Equation 6 in the right column of Page 5, the first constraint should be $\sum_{j \in S} \hat{t}_{j} \leq \tau$, not " $\leq S$ ".
2. Figure 6 in the right column of Page 6 should be updated to:

3. In Figure 8(a) in the left column of Page 7, the colorbar should be "ratio of relative error: tensor to matrix", not "matrix to tensor".
4. In Section A. 2 in the left column of Page 10, the list of meta-test UCI datasets should be updated to:
banknote-authentication, blood-transfusion-service-center, breast-cancer-wisconsin-diagnostic, breast-cancer-wisconsin-original, breast-cancer-wisconsin-prognostic, chess-king-rook-vs-kingpawn, cnae-9, congressional-voting-records, connectionist-bench, connectionist-bench-sonar, contraceptive-method-choice, cylinder-bands, haberman-survival, heart-disease-cleveland, heart-disease-hungarian, heart-disease-va, hepatitis, hill-valley, hill-valley-noise, horse-colic, imagesegmentation, indian-liver-patient, iris, libras-movement, mammographic-mass, monks-problems-2, ozone-level-detection-eight, ozone-level-detection-one, parkinsons, pen-based-recognition-handwritten-digits, planning-relax, qsar-biodegradation, seeds, seismic-bumps, statlog-project-german-credit, statlog-project-landsat-satellite, thoracic-surgery, thyroid-disease-allbp, thyroid-disease-allhyper, thyroid-disease-allhypo, thyroid-disease-allrep, thyroid-disease-ann-thyroid, thyroid-disease-dis, thyroid-disease-new-thyroid, thyroid-disease-sick, thyroid-disease-sickeuthyroid, thyroid-disease-thyroid-0387, wall-following-robot-navigation-2, wall-following-robot-navigation-24, wall-following-robot-navigation-4.
